



Innovative GPS solutions for cost optimisation

General Description

The ACTiV E GPS AGPS50A Series with embedded GPS antenna enables high performance navigation and solid fix even for the most stringent applications in harsh GPS visibility environments.

It is based on the **high performance** features of the MediaTek 3329 single-chip architecture. Its **-165dBm** tracking sensitivity extends positioning coverage into place like urban canyons and dense foliage environment where the GPS usage was not possible before. **Water-proof** design, easiest and convenient connector allow to add GPS functionality to other electronic equipment.

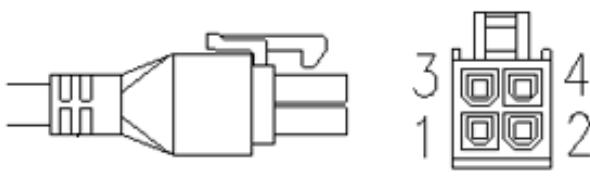
Applications

- LBS (Location Based Service)
- Vehicle navigation system
- PND (Portable Navigation Device)
- Timing application

Features

- Ultra high sensitivity: -165dBm
- 22 tracking/66 acquisition-channel receiver
- WAAS/EGNOS/MSAS/GAGAN support
- NMEA protocols (default speed: 9600bps)
- Internal back-up battery
- One serial port
- Embedded patch antenna
- Industrial temperature range
- RoHS compliant
- Tiny form factor

Pin Assignment



1. RX 2. TX 3. GND 4. 3.3V



AGPS50A Series Top View

Performance Specification

| Parameter | Specification | |
|--------------------------------|---|--|
| GPS receiver | | |
| Receiver Type | L1 frequency band, C/A code, 22 Tracking / 66 Acquisition-Channel | |
| Sensitivity | Tracking Acquisition | -165dBm -148dBm |
| Accuracy | Position Velocity Timing (PPS) | 3.0m CEP50 without SA(Typical Open Sky) 0.1m/s without SA 60ns RMS |
| Acquisition Time | Cold Start Warm Start Hot Start Re-Acquisition | 36s 33s 1s <1s |
| Power Consumption | Tracking Acquisition Sleep/Standy | <30mA @3.3V 45mA @3.3V TBD |
| Navigation Data Update Rate | 1Hz | |
| Operational Limits | Altitude Velocity Acceleration | Max 18,000m Max 515m/s Less than 4g |
| Antenna Specifications | | |
| Outline Dimension | 25 x 25 x 4.0 mm | |
| Center Frequency | 1575 ± 3 MHz | |
| Bandwidth | 10 MHz min | |
| Impedance | 50 Ω | |
| Axial Ratio | 3 dB max | |
| Polarization | RHCP | |
| Mechanical requirements | | |
| Dimension | 25 x 25 x 4.0 mm | |
| Weight | 50g | |
| Power consumption | | |
| VCC | 5V ±5% | |
| Current | 45mA(typical) | |
| Environment | | |
| Operating temperature | 40 ~ +85 °C (w/o backup battery) | |
| Storage temperature | 40 ~ +125 °C | |
| Humidity | ≤95% | |

Hardware Interfaces Configuration

Power Supply: Regulated power for the SKM50 series is required. The input voltage Vcc should be 3.3V, current is no less than 45mA. Suitable decoupling must be provided by external decoupling circuitry(10uF and 1uF). It can reduce the Noise from power supply and increase power stability.

UART Ports: The SKM50 series supports one full duplex serial channels UART. The serial connections are at 2.85V LVTTL logic levels, if need different voltage levels, use appropriate level shifters. the data format is however fixed: X, N, 8, 1, i.e. X baud rate, no parity, eight data bits and one stop bit, no other data formats are supported, LSB is sent first. The modules default baud rate is set up 9600bps. The RX & TX recommended to pull up (10KΩ). It can increase the stability of serial data.

| Pin No. | Pin name | I/O | Description | Remark |
|------------------|----------|-----|-------------------------------|-------------------------|
| UART Port | | | | |
| 1 | RX | I | TTL:VOH≥0.75 *VCC VOL≤0.25VCC | UART Serial Data Input |
| 2 | TX | O | TTL:VIH≥0.7 *VCC VIL≤0.3 *VCC | UART Serial Data Output |
| 3 | GND | G | Power Ground | Reference Ground |
| 4 | VCC | P | Power Supply | VCC:3.3V±10% |

Software Protocol

NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx where xxx is a three-letter identifier of the message data that follows. NMEA messages have a checksum, which allows detection of corrupted data transfers.

The ACTivE GPS AGPS50A supports the following NMEA-0183 messages: GGA, GLL, GSA, GSV, RMC VTG, ZDA. The module default NMEA-0183 output is set up GGA, GSA, RMC, GSV, and default baud rate is set up 9600bps.

Table 1: NMEA-0183 Output Messages

| NMEA Record | Description | Default |
|-------------|--|---------|
| GGA | Global positioning system fixed data | Y |
| GLL | Geographic position—latitude/longitude | N |
| GSA | GNSS DOP and active satellites | Y |
| GSV | GNSS satellites in view | Y |
| RMC | Recommended minimum specific GNSS data | Y |
| VTG | Course over ground and ground speed | N |
| ZDA | Date and Time | N |

GGA-Global Positioning System Fixed Data

This sentence contains the position, time and quality of the navigation fix.

See RMC for Fix Status, Fix Mode, Fix Date, Speed, and True Course.

See GSA for Fix Type, PDOP, and VDOP.

\$GP\$GGA,021514.000,2232.1799,N,11401.1823,E,1,6,1.25,84.0,M,-2.2,M,,*74

Table 2: GGA Data Format

| Name | Example | Units | Description |
|------------------------|------------|--------|--|
| Message ID | \$GPGGA | | GGA protocol header |
| UTC Position | 021514.000 | | hhmmss.sss |
| Latitude | 2232.1799 | | ddmm.mmmm |
| N/S indicator | N | | N=north or S=south |
| Longitude | 11401.1823 | | dddmm.mmmm |
| E/W Indicator | E | | E=east or W=west |
| Position Fix Indicator | 1 | | See Table 2-1 |
| Satellites Used | 6 | | Range 0 to 12 |
| HDOP | 1.25 | | Horizontal Dilution of Precision |
| MSL Altitude | 84.0 | meters | Altitude (referenced to the Ellipsoid) |
| AltUnit | M | meters | Altitude Unit |
| GeoSep | -2.2 | meters | Geoidal Separation |
| GeoSepUnit | M | meters | Geoidal Separation Unit |
| Age of Diff.Corr. | <Null> | second | Null fields when it is not Used |
| Diff.Ref.Station ID | <Null> | | Null fields when it is not Used |
| Checksum | *74 | | |
| EOL | <CR> <LF> | | End of message termination |

Table 2-1: Position Fix Indicators

| Value | Description |
|-------|---------------------------------------|
| 0 | Fix not available or invalid |
| 1 | GPS SPS Mode, fix valid |
| 2 | Differential GPS, SPS Mode, fix valid |

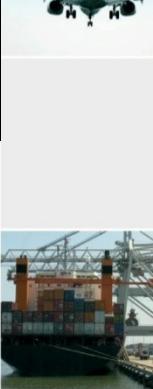
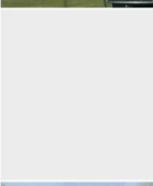
GLL-Geographic Position – Latitude/Longitude

This sentence contains the fix latitude and longitude.

\$GPGLL,2232.1799,N,11401.1824,E,021513.000,A,A*50

Table 3: GLL Data Format

| Name | Example | Units | Description |
|---------------|------------|-------|--|
| Message ID | \$GPGLL | | GLL protocol header |
| Latitude | 2232.1799 | | ddmm.mmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 11401.1824 | | dddmm.mmmm |
| E/W Indicator | E | | E=east or W=west |
| UTC Position | 021513.000 | | hhmmss.sss |
| Fix Status | A | | A=data valid or V=data not valid |
| Fix Mode | A | | A=autonomous, N = No fix, D=DGPS, E=DR |
| Checksum | *50 | | |
| EOL | <CR> <LF> | | End of message temination |



GSA-GNSS DOP and Active Satellites

This sentence contains the mode of operation, type of fix, PRNs of the satellites used in the solution as well as PDOP, HDOP and VDOP.

\$GPGSA,A,3,26,05,18,15,27,29,,,,,,1.52,1.25,0.87*0F

Table 4: GSA Data Format

| Name | Example | Units | Description |
|----------------------|-----------|-------|--|
| Message | \$GPGSA | | GSA protocol header |
| Mode 1 | A | | See Table 4-2 |
| Mode 2 | 3 | | See Table 4-1 |
| ID of satellite used | 26 | | Sv on Channel 1 |
| ID of satellite used | 05 | | Sv on Channel 2 |
| ... | ... | | ... |
| ID of satellite used | <Null> | | Sv on Channel 12 (Null fields when it is not Used) |
| PDOP | 1.52 | | Position Dilution of Precision |
| HDOP | 1.25 | | Horizontal Dilution of Precision |
| VDOP | 0.87 | | Vertical Dilution of Precision |
| Checksum | *0F | | |
| EOL | <CR> <LF> | | End of message termination |

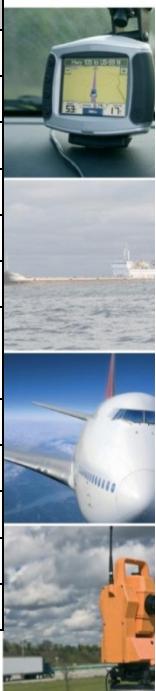


Table 4-1: Mode 1

| Value | Description |
|-------|-------------------|
| 1 | Fix not available |
| 2 | 2D Fix |
| 3 | 3D Fix |



Table 4-2: Mode 2

| Value | Description |
|-------|---|
| M | Manual-forced to operate in 2D or 3D mode |
| A | Automatic-allowed to automatically switch 2D/3D |



GSV-GNSS Satellites in View

This sentence contains the PRNs, azimuth, elevation, and signal strength of all satellites in view.

\$GPGSV,3,1,12,15,79,333,42,42,50,127,,29,45,263,44,02,36,124,30*7E

\$GPGSV,3,2,12,26,36,226,34,05,35,046,22,27,33,161,29,21,16,319,*7D

\$GPGSV,3,3,12,10,15,066,31,18,14,285,45,24,12,319,15,08,09,047,18*7E

Table 5: GGA Data Format

| Name | Example | Units | Description |
|--------------------|-----------|---------|---|
| Message ID | \$GPGSV | | GSV protocol header |
| Number of Message | 3 | | Total number of GSV sentences (Range 1 to 3) |
| Message Number | 1 | | Sentence number of the total (Range 1 to 3) |
| Satellites in View | 12 | | Number of satellites in view |
| Satellite ID | 15 | | Channel 1(Range 01 to 32) |
| Elevation | 79 | degrees | Channel 1(Range 00 to 90) |
| Azimuth | 333 | degrees | Channel 1(Range 000 to 359) |
| SNR(C/NO) | 42 | dB-Hz | Channel 1(Range 00 to 99, null when not tracking) |
| ... | | | ... |
| Satellite ID | 02 | | Channel 4(Range 01 to 32) |
| Elevation | 36 | degrees | Channel 4(Range 00 to 90) |
| Azimuth | 124 | degrees | Channel 4(Range 000 to 359) |
| SNR(C/NO) | 30 | dB-Hz | Channel 4(Range 00 to 99, null when not tracking) |
| Checksum | *7E | | |
| EOL | <CR> <LF> | | End of message termination |

Depending on the number of satellites tracked multiple messages of GSV data may be required.

RMC-Recommended Minimum Specific GNSS Data

This sentence contains the recommended minimum fix information.

See GGA for Fix Quality, Sats Used, HDOP, Altitude, Geoidal Separation, and DGPS data.

See GSA for Fix Type, PDOP and VDOP.

\$GPRMC,023345.000,A,2232.1767,N,11401.1953,E,0.18,151.55,100410,,A*6B

Table 6: RMC Data Format

| Name | Example | Units | Description |
|------------------------------|------------|---------|--|
| Message ID | \$GPRMC | | RMC protocol header |
| UTS Position | 023345.000 | | hhmmss.sss |
| Status | A | | A=data valid or V=data not valid |
| Latitude | 2232.1767 | | ddmm.mmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 11401.1953 | | dddmm.mmmm |
| E/W Indicator | E | | E=east or W=west |
| Speed Over Ground | 0.18 | Knots | |
| Course Over Ground | 151.55 | Degrees | True Course |
| Date(UTC) | 100410 | | ddmmyy |
| Magnetic variation | <Null> | Degrees | Null fields when it is not Used |
| Magnetic Variation Direction | <Null> | | E=east or W=west (Null fields when it is not Used) |
| Fix Mode | A | | A=autonomous, N = No fix, D=DGPS, E=DR |
| Checksum | *6B | | |
| EOL | <CR> <LF> | | End of message termination |

VTG-Course Over Ground and Ground Speed

This sentence contains the course and speed of the navigation solution.

\$GPVTG,148.81,T,,M,0.13,N,0.24,K,A*3D

Table 7: VTG Data Format

| Name | Example | Units | Description |
|-------------------|-----------|---------|---|
| Message ID | \$GPVTG | | VTG protocol header |
| Tcourse | 148.81 | Degrees | True Course |
| Reference | T | | T = True |
| Mcourse | <Null> | Degrees | Magnetic Course (Null fields when it is not Used) |
| Reference | M | | M = Magnetic (Null fields when it is not Used) |
| Speed over ground | 0.13 | Knots | Nautical Miles per Hour |
| Units | N | | Knots |
| Speed over ground | 0.24 | Km/hr | in Kilometers per Hour |
| Units | K | | Kilometer per hour |
| Mode | A | | A=Autonomous, N=No fix, D=DGPS, E=DR |
| Checksum | *3D | | |
| EOL | <CR> <LF> | | End of message termination |



ZDA-Date and Time

This sentence contains UTC date & time, and local time zone offset information.

\$GPZDA,023345.000,10,04,2010,,*50

Table 8: ZDA Data Format

| Name | Example | Units | Description |
|--------------------|------------|-------|--|
| Message ID | \$GPZDA | | ZDA protocol header |
| UTC Time | 023345.000 | | hhmmss.sss |
| Day | 10 | | UTC time: day (01 ... 31) dd |
| Month | 04 | | UTC time: month (01 ... 12) mm |
| Year | 2010 | | UTC time: year (4 digit year) yyyy |
| local zone hours | <null> | | Local Time Zone Offset Hours (Null fields when it is not Used) |
| local zone minutes | <null> | | Local Time Zone Offset Minutes (Null fields when it is not Used) |
| Checksum | *50 | | |
| EOL | <CR> <LF> | | End of message termination |



ACTE Sp. z o.o. reserves the right to specification changes without notice