

AirPrime XA1100/XM1100



41111189 Rev 1

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1	June 23, 2017	Initial revision in SWI Template

->> Contents

Introduction
Caution
Packing Contents
Function Description
Function Testing
Preparation for Power and Data Communication (XA1100, XM1100 not using 3D-Fix function)
Application for the various RF reception
Software Usage
System Requirements
USB Driver and GNSS Tool
Installing the USB Driver
Using GNSS Tool
RTCM Hardware Settings16
Getting RTCM data via RS232port16
RTCM Software Settings17
Troubleshooting
Setup Troubleshooting
Causes of Poor GPS Signals

>> 1: Introduction

The main purpose of this EV-Kit is to simplify the evaluation process for GPS modules and to help testers operate our products with convenience and ease.

This device can communicate with computer devices via USB, and must be used in conjunction with the GNSS Tool software application. You can record all GPS module data such as satellites' status, time-to-first-fix (TTFF), date and time.

If you evaluate the RTCM function, it will show you how to run the GNSS Tool with the EV-Kit via RS232 (DB-9 Connector).

The EV-Kit was divided into two series, basing on the various modules listed below.

Left: With External Antenna (series 1). Right: Built-in Switch Antenna input (series 2).



Figure 1-1: Left: lovry 2. Right: XA1100





Figure 1-2: XM1100

Caution

- Global position system (GPS) is the property of American Ministry of National Defense; they are fully responsible for the preciseness and maintenance of the system. Any changes they have implemented to the system in the future may enhance or deteriorate the effectiveness and performance of the received GPS data.
- The GPS signal might be cut-off or become seriously weakened if you
 operate the EV-kit inside any infrastructures such as buildings, tunnels, or
 nearby any huge objects and/or obstructions. The kit has not malfunctioned
 and will operate properly again once it receives clear GPS signals (works
 best under open sky).
- To avoid damaging the intricate electronic components and circuitry, please do not place the EV-Kit directly under the sun for long periods of time.

Packing Contents

- User Manual / Software Application Program
- CP210X USB Bridge VCP driver
- GNSS Tool with user manual
- EV-Kit user manual

Note: These items will be delivered by *E*-mail. Please contact your dealer for the items for more information.

- USB Cable
- EV-Kit with Main Board and GPS Module
- External Antenna

>> 2: Function Description

The following figures illustrate and describe the EV-Kit device:



Figure 2-1: Compatible Models (Series 1): lovry 2



Figure 2-2: Compatible Models (Series 1): XM1100



Figure 2-3: Compatible Models (Series 2): XA1100

3: Function Testing

Preparation for Power and Data Communication (XA1100, XM1100 not using 3D-Fix function)

- Connect the USB cable with the PC.
 The EV-Kit will turn on with USB power and the EV-Kit will transfer communi
 - cation data with the PC.Make sure Power LED Indicator (D1) light is lighted on.
- Turn on the power for the GPS module: The switch enables the LDO to supply power for the GPS Module. Please refer to the figures shown below.
 - a. Once the Power LED Indicator(D1) is on and main board enable switch(SW1) is on, the initial state will be the following:

3D Fix LED Indicator (D2) blinks (blue light).

1PPS LED Indicator (D3) is off (green light).

b. Once the module is in the status of FIX:

3D Fix LED Indicator (D2) is off.

1PPS LED Indicator (D3) green is blinking.



Figure 3-1: Components

Application for the various RF reception

1. Use an External Antenna with the GPS Module as shown in Figure 3-2. Compatible Model (series1): Ivory 2, XM1110.



Figure 3-2: Using an External Antenna

2. Connect an External Antenna with the GPS Module as shown in Figure 3-3. Compatible Model (series 2): XA1100.



Figure 3-3: Using an External Antenna

As soon as you connect an external antenna, the internal RF switch will wire the RF signal from external antenna. If the external antenna is removed, it will autoswitch to the built-in patch antenna.

Note: the module will detect and connect to the external antenna when it begins to consume >4mA current.

>> 4: Software Usage

System Requirements

- Operation System: Windows OS 7, 8, and 10
- USB Driver: CP210x VCPInstaller.zip
- GUI Tool: GNSS Tool
 - Microsoft .NET Framework 4.5
 - Microsoft Visual C++ 2015 Redistributable Package (x86)

USB Driver and GNSS Tool

Before setting up the connection between the module and the PC, please download and install the VCP driver from the following link.

From Silicon Labs Web-side (CP210x USB to UART Bridge VCP Drivers):

http://www.silabs.com/products/mcu/Pages/USBtoUARTBridgeVCPDrivers.aspx

You will need the EV-Kit USB Driver (CP210xVCP) and GNSS Tool.exe to operate the EV-Kit.

Important: Please check whether you have the correct USB driver before you proceed to the next step. Without the correct driver, the EV-Kit will not function.

Installing the USB Driver

1. Double click CP210x_VCP_Win.exe to begin driver installation:



2. Click Install:

Δ

🛃 Silicor	Laboratories CP210x US	B to UART Bridge Driver Installer	X
*	Silicon Laboratories Silicon Laboratories CP210x	USB to UART Bridge	
Install	ation Location:	Driver Version 4.40	
C:\	Program Files\Silabs\MCU\CP2	210×\	
Ch	ange Install Location	Install	

Figure 4-2: Starting the Installation Process

- **3.** After the installation is complete, you may need to restart your computer. Please follow the instructions on screen to restart your computer.
- 4. After the computer restarted, right click on **My Computer** and select **Manage**:



Figure 4-3: Selecting Manage

 Left click Device Manager and select Ports (COM &LPT). Check to see if a device named Silicon Labs CP210x USB to UART Bridge (COM#) is present. If so, the EV-Kit is set up and ready for use.



Figure 4-4: Accessing the Port Properties

"COM9" in this example represents the virtual COM port number generated for the USB connection to the EV-Kit. This generated COM port value must match the COM port value in the program setting for the application to establish proper communication with the EV-Kit.

After completing the installation, please proceed to Using GNSS Tool.

Using GNSS Tool

Microsoft Framework 4.5 or higher is required before you launch the GNSS Tool software on your PC.

Double click **GNSSTool.exe** to start the application, the main screen of the program is shown here:



Figure 4-5: GNSSTool main screen

- 1. Command Tx and Rx List: clicking on this menu item will display the Command window.
- 2. NMEA List: clicking on this menu item will display a window with NMEA information.
- 3. CNR Signal: clicking on this menu item will display the CNR signal window.
- 4. Sky View: clicking on this menu item will display a window with a sky view of satellites.
- 5. Statistics Plot: clicking on this menu item will display the statistics plot window.
- 6. Map: clicking on this menu item will display the map window.

After the Sierra Wireless EV-Kit is connected with the PC, please choose the correct **<COM Port>** and **< Baud Rate >** then click the **OK** button and select the appropriate value.

When users click the *Open Communication* menu item or toolbar button, a set up dialog will pop up as shown here:

Open COM Port	
COM Port:	<u></u>
Baud Rate:	115200 👻
Cancel	OK

Figure 4-6: COM Port Dialog

If you want more information about the GNSS Tool software, refer to the Sierra Wireless GNSS Tool Operation Manual.

>> 5: RTCM Hardware Settings

Compatible Models: lovry 2

Getting RTCM data via RS232port

Connect the RS232 cable to the EV-Kit. The RS232 cable is connected to the EV-Kit RS232 port (J2) and to the RTCM server (host computer) as shown below:



Figure 5-1: RS232 Connection

>> 6: RTCM Software Settings

The Ntrip client function can connect to the specified Ntrip caster and create the RTCM streaming. Before connecting to an Ntrip caster, please set up the required parameters properly.

Clicking the drop down arrow show the Settings menu:



Figure 6-1: Settings Menu

After clicking the *Settings* menu, the *Ntrip Client Settings* dialog pop up as appears as shown below:

			Address:	
Name	Version	<u>^</u>	www.igs-in.net	
ABMF0	RTCM 3.1	-	a a a sigo spinor	
ADISO	RTCM 3.0	-	Port:	
ADIS1	RTCM 3.0		2101	
AJACO	RTCM 3.1		1	
ALBH0	RTCM 3.0		Username:	
ALGO0	RTCM 3.0			
ALIC0	RTCM 3.1		Personal	
ASCG1	RTCM 3.1		1 1 0.55W 010.	
AUCK0	RTCM 3.0		1	
AZU10	RTCM 3.1		1	
BNDY0	RTCM 3.0		Location	
BOR10	RTCM 2.3		Fived	Dynami
BRAZO	RTCM 3.0		I LNOU	O Dynami
BRSTO	RTCM 3.1		Latitude	N
BRUXO	RTCM 3.1		Doutomo.	
BUCU0	RTCM 3.1		Longitude:	E
BZRGO	RTCM 2.3		1	
CAS10	RTCM 3.1		Carrial Port	
CEDU0	RTCM 3.1			
CEEU0	RTCM 3.0	_	Serial Port:	
CUTIO	DTCM 20			
•			Baud Rate:	

Figure 6-2: NTrip Client Settings

- 7. Choose a proper stream which meets yours RTCM version.
- **8.** Input the address and port numbers of the specified caster and the authorized username and password to log in.
- **9.** Designate a fixed location by inputting the latitude and longitude. This reference location information will be sent to the Ntrip caster to get more accurate RTCM correction data.
- 10. Choose the specified serial port and baud rate.

After the set up is complete click the **RTCM** button to enable the RTCM function as shown here:

	Step 2			
	🗛 NMEA	Information		8
	Informatic	n NMEA		
	Sente	Field	Value	-
	RMC	UTC Date	2016-12-13	
	GGA	UTC Time	05:35:14.000	
	GGA	Latitude	23.118724 N	
	GGA	Longitude	120.274120 E	E
	GGA	Quality	DGPS	
o	GGA	Fix Mode	3D	
Step 1	RMC	Navigation Status	Valid	
	GSA	Selection Mode	A	
Ella Alfanta Alfanta Alfanta	GGA	Base Altitude	17.806	
File View Window About	GGA	Antenna Altitude	5.794	
	¥ TG	Speed (km/h)	0.4	
🗄 🔍 👝 🍋 🦾 🔤 🚺 FW 🧮	RMC	Speed (knots)	0.03	*
: 🖌 🛡 🧀 🎬 🖬 Ver.	•		III	۴

Figure 6-3: Clicking the RTCM button to enable the RTCM function.

>> 7: Troubleshooting

Setup Troubleshooting

Table 7-1: Troubleshooting Causes and Solutions

Problem	Possible Cause	Solution
Cannot find GPS device	USB was not set up properly	Check to see if the EV-Kit was set up properly, and make sure that the device is receiving enough power through the USB cable (Red LED should light up continuously).
No NMEA data or GPS signals	 USB was not set up properly. COM Port or Baud rate value is incorrect. 	 Check to see if the USB connector to the PC or EV-Kit is tightly connected. Double check to see if the proper COM Port and Baud rate value are selected.
Poor GPS Signal Reception	 If it is used inside a vehicle, the anti- sunscreen film on the windshield may interfere and weaken the GPS signal. 	For both problems, the user may apply the External Active Antenna with the EV-Kit, and then place the antenna on top of the car's roof to improve signal reception.
	2. The vehicle is traveling through an area with a dense overhead canopy: such as forest, buildings, open tunnels etc.	

Note: if these troubleshooting steps do not solve the problem, please contact us or send it back to us for testing and repair.

Causes of Poor GPS Signals

It is possible to have weak GPS signal in the following situations:



Inside a tunnel, where the GPS signal is blocked.
Underneath infrastructure (e.g. bridge), where the GPS signal is blocked.
Inside a building, where the GPS signal is blocked.



Table 7-2: Examples where Poor GPS Signals may Occur

- If the EV-Kit is used inside a car which has anti-sunlight films on the windshield and windows, the GPS signal will be weakened severely, and may result in no GPS reception.
- GPS satellites are property of United States Army. Sometimes they will tunedown the accuracy for unknown reasons. In such cases, the GPS position may not be accurate.