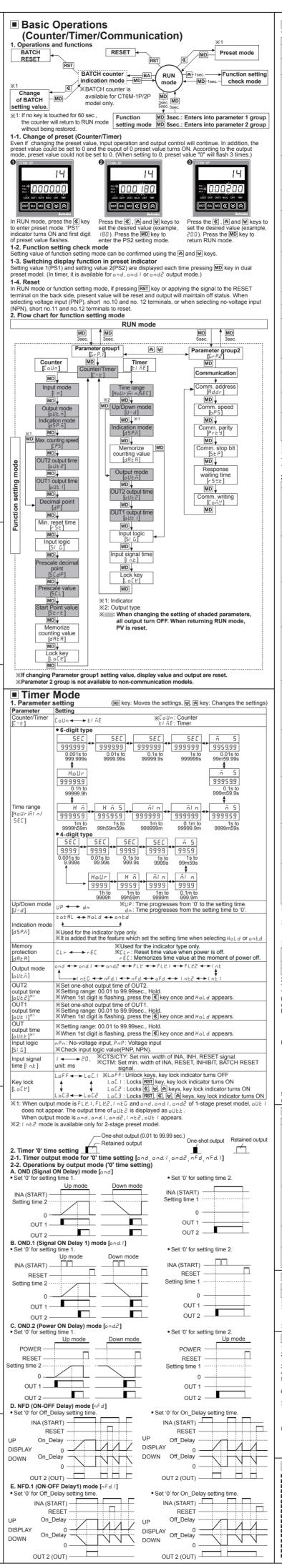


Power OFF $\overset{\bullet}{\rightarrow}$ change settings \rightarrow power ON \rightarrow press $\boxed{\text{RST}}$ key or input signal (min. 20ms)



Counter Mode (MD key: Moves the settings, ⊌, key: Changes the settings) Parameter Setting Ж[aUn: Counte CoUn ← → biñE E! ñE: Timer Ud-[←→ UP ←→ UP- 1 ←→ UP-2 ←→ dn ←→ dn- 1 ←→ dn-2 ←→ Ud-R ←→ Ud-b Input mode • Input mode is UP, UP- 1, UP-2 or dn, dn- 1, dn- F ← → n ← → E ← → r ← → E ← → P ← → 9 ← → 9 [oUt.ñ] Input mode is Ud-B Ud-b Ud-F "If max. counting speed is 5kcps, and output mode is d, max. counting speed is automatically changed as 30cps, factory default. In case of the indicator

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*In case of the indicator type, [d5P.ñ] is displayed. mode XIt is the added function to set the preset value when HoLd ← ► totAL [d5P.5] selecting HoLd.

*Max. counting speed is when duty ratio of INA or INB input signal is 1:1. It is applied for INA, or INB input as same. Max. counting 30 ← 12 ← 52 ← 102 ← 1 *When output mode is d, set max. counting speed [CP5] one among 1cps, 30cps, or 1kcps.

**Set one-shot output time of OUT2. OUT2 XSetting range: 00.01 to 99.99sec.
 XWhen input mode is F, n, 5, E, d, o UE ≥ does not appear. (fixed as HOLD)
 XSet one-shot output time of OUT1. XSetting range: 00.01 to 99.99sec., Hold. output time3 OUT %Setting range: 00.01 to 99.99sec. %When input mode is F, p, 5, E, d, p UEE does not appear. (fixed as HOLD) output time* [oUt.t] • 6-digit type point* • 4-digit type

**Decimal point is applied to counting value and setting value Min. rese 1 ← → 20, unit: ms *Set min. width of external reset signal input. time [-5+] Input logic nPn: No-voltage input, PnP: Voltage input *Check input logic value (PNP, NPN). [5/6] 6-digit type Prescale decimal point*2 4-digit type ※Decimal point of prescale should not [5 C.dP] set smaller than decimal point [dP]. Setting range of prescale value 6-digit type: 0.00001 to 99999.9, 4-digit type: 0.001 to 999.9

Setting range (linked with decimal point [dP]):
6-digit type: 0.00001 to 999999, 4-digit type: 0.001 to 9999 value [5 [L] Start point value *When input mode is dn, dn-1, dn-2, start point value does not appear.

*£Lr: Resets the counting value when power OFF. [5±r±] Memory rEI: Maintains the counting value when power OFF. protection (memory protection)

**XL.oFF: Unlock keys, key lock indicator turns OFF [dRER] L.oFF ← ► L o [. 1 Key lock

[Loft]

Loft : Locks [85] key, key lock indicator turns ON

Loft: Locks [8, ♥], ♠] keys, key lock indicator turns ON

Loft: Locks [8, ♥], ♠] keys, key lock indicator turns ON

*1: For 1-stage preset model, out 1 does not appear. The output time of out ≥ 2 is displayed as out ≥ 2. ※2: Decimal point and prescale decimal point Decimal point: Set the decimal point for display value regardless of prescale value.
 Prescale decimal point: Set the decimal point for prescale value of counting value regardless of decimal point of display value. 2. Input mode INA H TO TO TO TO TO INB is no counting input. [Up] When INB is counting input, INA is no counting input. 99999 UP - 1 [Up-1] rising (上), it counts. XINA: Counting input INA L When INA input signal is falling (L) , it counts. XINA: Counting input [Up-2] ※INB: No counting input INA HATALAN When INA is counting input. INB is no counting input. dn [Down] When INB is counting input, INA H TO TO TO **XWhen INA input signal is** rising (🖵) , it counts. dn - 1 [Down-1] No counting XINA: Counting input INA H [Down-2] ※INB: No counting input INA HAAAAAAAAAAA INB: Counting command 100 *When INB is "L", counting [Up/ 1 2 3 4 3 2 1 2 3 4 counting command is down .

**INA: Up counting input INB: Down counting input When INA and INB input signals are rising (_ f) at the same time, it maintains previous counting value. output A, B phase with Ud-[^{∗1} counter input, INA, INB, set 村村 [Up/ Down-C] different input [Ud-[] for counter operation. ×1: For selectable no-voltage input (PNP), ON OFF ON OFF voltage input (NPN) model. *A: over min. signal width, B: over than 1/2 of T.on T.off min. signal width. If the signal is smaller than these width, it may cause counting error (±1). *The meaning of "H". "L" Input method | Voltage input Counting speed Min. signal width Character (PNP)
H 5-30VDC (NPN) 0-2VDC 5kcps 3. Prescale function This function is to set and display calculated unit for actual length, liquid, position, etc. It is called "prescale value" for measured length, liquid, or position, etc per 1 pulse. For example, when moving L, the desired length to be measured, and P, the number of pulses per 1 revolution of a rotary encoder, occurs, prescale value is LIP. E.g.) Positioning control by counter and encoder [Diameter (D) of pulley connected with Pulley encoder= 22mm, the number of pulses by

1 rotation of encoder=1.0001 *Prescale value = π × Diameter (D) of pulley The number of pulses by 1 rotation of encoder 3.1416 × 22

Motor control system

1000 = 0.069mm/pulse Set decimal point[dP] as [------], prescale decimal point [5LdP] as [------], prescale value [5LL] as [0.069] at function setting mode. It is available to control conveyer position by 0.1mm unit.

■ Factory Default 6-digit type: dSP.ñ 4-digit type: - .- - -6-digit type: 1.00000 CP5 30 SCL 4-digit type: 1.000 oUt2(oUt.t) Hold (fixed) 6-digit type: 0.00 /s-999.999s Hour/AI n/SEC UE2(oUE.E) 4-digit type: 0.00 /s-9.999s

Error Display and Output Operation Error description
Setting value is 0. Change the setting value anything but 0. When error occurs, the output turns OFF. When 1st setting value is set as 0 (zero), OUT1 maintains OFF.

When 2nd setting value is smaller than 1st setting value, 1st setting value is ignored and only

OUT2 output operates. XIndicator model does not have error display function.

Cautions during Use Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
 2. 24-48VDC, 24VAC power supply should be insulated and limited voltage/current or Class 2, SELV

power supply device.

3. Use the product, 0.1 sec after supplying power.

When supplying or turning off the power, use a switch or etc. to avoid chattering.
 Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the

power.

6. In case of contact input, set count speed to low speed mode (1cps or 30cps) to operate. If set to high speed mode (1k, 5k, 10kcps), counting error occurs due to chattering.

7. Keep away from high voltage lines or power lines to prevent inductive noise.

Reep away from high voltage lines of power lines to prevent inductive noise.

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

Shis product may be used in the following environments.

Ondoors (in the environment condition rated in 'Specifications')

②Altitude max. 2,000m Pollution degree 2
 Installation category II

Major Products ■ Photoelectric Sensors ■ Temperature Controllers
■ Fiber Optic Sensors ■ Temperature/Humidity 1 Fiber Optic Sensors
Door Sensors
Door Side Sensors
Door Side Sensors
Proximity Sensors
Proximity Sensors
Rotary Encoders
Connector/Sockets
Switching Mode Power Supplies
Control Switches/Lamps/Buzzers
(To Terminal Blocks & Cables
Stepper Motors/Drivers/Motion Col
Graphic/Logic Panels Panel Meters

Autonics Corporation HEAD QUARTERS

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