Autonics

ROTARY ENCODER(INCREMENTAL TYPE) E40S/E40H/E40HB/E80H SERIES



Thank you for choosing our Autonics product. Please read the following safety considerations before use.

Safety Considerations

%Please observe all safety considerations for safe and proper product operation to avoid hazards

 $leph \Lambda$ symbol represents caution due to special circumstances in which hazards may occur.

Warning Failure to follow these instructions may result in serious injury or death ▲ Caution Failure to follow these instructions may result in personal injury or product damage.

▲ Warning

- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in fire, personal injury, or economic loss.

 2. Install on a device panel to use.
- Failure to follow this instruction may result in fire.
- 3. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire.
- 4. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire
- 5. Do not disassemble or modify the unit.
 Failure to follow this instruction may result in fire

▲ Caution

- 1. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage.
- 2. Do not short the load. Failure to follow this instruction may result in product damage by fire
- Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion
- 4. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage.

Ordering Information

E40S	6	- 5000	- 3	- N	- 24	
Series	Shaft diameter	Pulses / Revolution	Output phase	Output	Power supply	Cable
E40S	*Ø6mm Ø8mm	*1,*2,*5,10,*12,15,20, 23,25,30,35,40,45,50,	2: A, B	T: Totem pole		
	Inside diameter	60,75,100,120,125,150 192,200,240,250,256,	3: A, B, Z	output		
E40H E40HB	Ø6mm *Ø8mm Ø10mm Ø12mm	300,360,400,500,512, 600,800,1000,1024,1200, 1500,1800,2000,2048, 2500,3000,3600,5000	4: A, \overline{A} , B, \overline{B} 6: A, \overline{A} , B, \overline{B} , Z, \overline{Z}	collector output 1	5: 5VDC ±5% 24: 12-24VDC	No mark : Radial cable type C(※) : Radial cable connector type
E80H	*Ø30mm Ø32mm	60,100,360,500 512,1024,3200	3: A, B, Z 6: A, Ā, B, B̄, Z, Z̄	L: Line Driver output		
*" * " ir *1, 2, 5	*Cable length : 250mm					

■ Control Output Diagram

Totem Pole output		NPN open collector output							
Rotary encoder circuit	Load connection	Rotary encoder circuit	Load connection						
≥ *	Max. 30mA Coad Coutput (%2) T - Coc current Load COV	Main circuit	Output + Sink current: Max. 30mA						
Voltage output		Line Driver output							
Rotary encoder circuit	Load connection	Rotary encoder circuit	Load connection						
Main circuit	Source current: Max.10mA Output Load OV	Main circuit	A phase output + A phase output - OV						

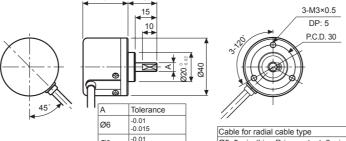
- *The output circuit of A, B, Z phase are the same.(Line Driver output is A, A, B, B, Z, Z phase) *Totem Pole output can be used for NPN open collector type(*1) or voltage output type(*2).
- XThe above specifications are subject to change and some models may be disconti
- **Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

Specifications

In			Ø40mm Shaft type		Ø40mm Hollow shaft Built- in type	Ø80mm Hollow shaft type			
-			E40S	E40HT	E40HB	E80H			
3			E40S	E40H	E40HB	E80H			
2			E40S	E40H	E40HB	E80H			
	Lin	e Driver output	E40S		E40HB	E80H			
R	Resolution(PPR)		*1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000 (Not indicated type is available to customize)						
О	utpu	phase ^{×1}	A, B, Z phase(Line Driver output: A, Ā, B, B, Z, Z phase)						
	Phase difference between		Outside the search of Debug T. T. T. T. J. J. T. J.						
	ou	tput	Output between A and B phase: $\frac{T}{4} + \frac{T}{8}$ (T= 1cycle of A phase)						
	-		Low ☞ Load current: Max. 30mA, Residual voltage: Max. 0.4VDC=						
	3	Totem Pole output	High @ Load current: Max. 10mA, Output voltage(Power voltage 5VDC=): Min.(Power voltage-2.0)VDC=, Output voltage(Power voltage 12-24VDC=): Min. (Power voltage-3.0)VDC=						
	Gootma Custous	NPN open collector output	tput Load current: Max. 30mA, Residual voltage: Max. 0.4VDC:						
	3	Voltage output	Load current: Max. 10mA, Residual voltage: Max. 0.4VDC=						
	5 5		Low Load current: Max. 20mA, Residual voltage: Max. 0.5VDC ==						
1 2	g C	Line Driver output	High & Load current: Max20mA, Output voltage(Power voltage(Fower voltage(Power voltage 12-24VDC=): Min. (Power voltage-3.0)VDC=						
19	5	Totem Pole output		-		-			
Cleotrical coordination	Response	NPN open collector	Max. 1//s (Cable length: 2m, I sink=20mA)						
1 -	<u>" &</u>	output							
1 5	ses es	Voltage output							
3	2		Max. 0.5 (Cable length: 2m, I sink=20mA)						
u	Ma	x. Response frequency	300kHz			200kHz			
	Po	wer supply	5VDC= ±5%(Ripple P-P: Max. 5%) 12-24VDC= ±5%(Ripple P-P: Max. 5%)						
	Си	rrent consumption	Max. 80mA (disconnection of the load), Line Driver output: Max. 50mA(disconnection of the load)						
	Ins	ulation resistance	Min. 100llQ(at 500VDC megger between all terminals and case)						
	Die	electric strength	750VAC 50/60Hz for 1 minute(Between all termials and case)						
	Co	nnection	Radial cable type, Radial cable connector type						
7	छ Starting torque		Shaft Type: Max. 40gf·cm(0.004N·m), Hollow Type	: Max. 50gf·cm(0.005N·m)		Max. 200gf·cm(0.02N·m)			
1.5	Moment of inertia Shaft loading		Max. 40g·cm ² (4×10 ⁻⁶ kg·m ²)			Max. 800g·cm²(8×10 ⁻⁵ kg·m²)			
1 2			Radial: 2kgf, Thrust: 1kgf	Radial: 5kgf, Thrust: 2.5kgf					
1			5,000rpm	3,600rpm					
			15.55000pm 15.5500pm 15.55						
			Max. 50G	iii.) iii cadii X, 1, 2 dii caddii idi 2 libalb		Max. 75G			
	Ambient tempe.		-10 to 70 ℃, Storage: -25 to 85 ℃			max. 100			
E	nviro		35 to 85% RH, Storage: 35 to 90%RH						
Protection structure			UPSO(IEC Standards)						
			G5mm, 5-wire, Length: 2m, Shield cable(Line Driver output: Ø5mm, 8-wire)						
Cable			(AWG 4, 6 Min 4, 6 Mi						
			Ø6mm coupling(Standard),	1	-				
			Ø8mm coupling(Option)	Bracket					
Α			(((Except for Line Driver output)						
			Approx. 120g			Approx. 560q			
X1: 1, 2, 5, 12 PPR are output A, B phase only (But Line Driver output: A, A, B, B phase)									
*	※2: Max. allowable revolution≥ Max. response revolution [Max. response revolution(rpm) = Max. response frequency Resolution Resolution Resolution								

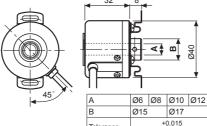
XEnvironment resistance is rated at no freezing or condensation

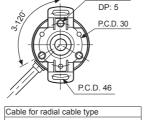
Dimensions OShaft type(E40S) OHollow shaft type(E80H)



Ø8 Ø5. 5-wire(Line Driver output: 8-wire). Length: 2000, Shield cable

OHollow shaft type(E40H)





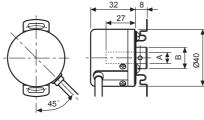
3-M3×0.5

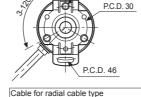
3-M3×0.5

DP: 5

Ø5 5-wire(Line Driver output: 8-wire)

OHollow shaft built-in type(E40HB)





※ A, B dimensions are the same as hollow shaft type(E40H) Ø5, 5-wire(Line Driver output: 8-wire), Length: 2000, Shield cable

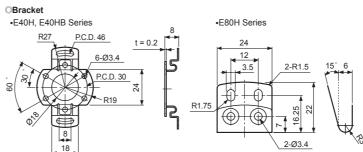
43 Shaft inner diameter standard 35 Ø30+0.0 Shaft inner diameter (option) • | • |

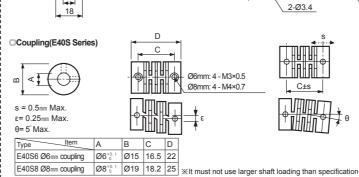
3.5

Cable for radial cable type

Length: 2000, Shield cable

Ø5. 5-wire(Line Driver output: 8-wire).





**Do not put strong impact when insert a coupling into shaft.
Failure to follow this instruction may result in product damage.
**Fix the unit or a coupling by a wrench under 0.15 N·m of torque.
*When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.

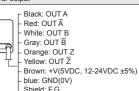
Connections

Radial cable type



White: UU1 B Orange: OUT Z Brown: +V(5VD - Brown: +V(5VDC, 12-24VDC ±5% Blue: GND(0V)

•Line Driver output

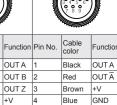


Non-using wires must be insulated.
 The shield cable and metal case of encoder must

be grounded(F.G.). **Do not apply tensile strength over 30N to the

ORadial cable connector type •Totem Pole output ●Line Driver output Voltage output

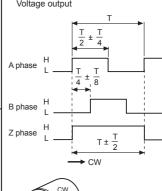




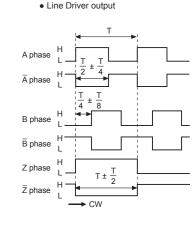
Black OUT A Black OUT A White OUT B Orange OUT Z Brown +V Blue GND White OUT B Shield F.G. Gray OUT B Orange OUT Z Yellow OUT Z Shield F.G.

Output Waveform

 Totem Pole output / NPN open collector output Voltage output



(unit: mm



Cautions during Use

- 1. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
 2. 5VDC, 12-24VDC power supply should be insulated and limited voltage/current
- or Class 2, SELV power supply device.
- 3. For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- 4. Ground the shield wire to the F.G. terminal.
- 5. When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- 7. For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication.
- 8. Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between
- This unit may be used in the following environments
- ①Indoors (in the environment condition rated in 'Specifications') ②Altitude max. 2,000m
- ③Pollution degree 2 (4) Installation category I

Major Products

■ Photoelectric Sensors
■ Temperature Controllers ■ Fiber Optic Sensors ■ Temperature/Humidity Transducers SSRs/Power Controllers

Door Sensors ■ Door Side Sensors

■ Counters Area Sensors ■ Panel Meters

■ Proximity Sensors ■ Tachometer/Pulse (Rate) Meters Pressure Sensors ■ Rotary Encoders

■ Display Units ■ Connector/Sockets ■ Sensor Controllers ■ Switching Mode Power Supplies

■ Control Switches/Lamps/Buzzers ■ I/O Terminal Blocks & Cables

Stepper Motors/Drivers/Motion Controllers

■ Graphic/Logic Panels ■ Field Network Devices

■ Laser Marking System (Fiber, CO₂, Nd; YAG) ■ Laser Welding/Cutting System

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